

MEITRACK T622/T622G User Guide





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Contents

1 Copyright and Disclaimer	4 -
2 Product Overview	4 -
2.1 Product Features	4 -
2.1.1 Garmin Navigator	4 -
2.1.2 Harsh Acceleration/Braking Alarm	4 -
2.1.3 Roaming Mode	5 -
2.1.4 CAN Bus Interface	5 -
2.1.5 GPS Data Filtering	5 -
2.1.6 Activating Output by Event	6 -
3 Product Functions and Specifications	6 -
3.1 Product Functions	6 -
3.1.1 Position Tracking	6 -
3.1.2 Anti-Theft	6 -
3.1.3 Other Functions	7 -
3.1.4 Functions of Optional Accessories	7 -
3.2 Specifications	7 -
4 T622/T622G and Accessories	8 -
5 Appearance	9 -
6 First Use	9 -
6.1 Installing the SIM Card	9 -
6.2 Charging the Device	10 -
6.3 LED Indicator	10 -
6.4 Configuring Device Parameters by Meitrack Manager	10 -
6.5 Tracking by Mobile Phone	11 -
6.6 Common SMS Commands	12 -
6.6.1 Setting Authorized Phone Numbers – A71	12 -
6.6.2 Setting the Smart Sleep Mode – A73	13 -
6.6.3 Setting GPS Data Filtering – D71	13 -
6.6.4 Setting Output Triggering – D72	13 -
6.6.5 Allocating GPRS Cache and GPS Log Storage Space – D73	14 -
7 Logging In to MS03 Tracking System	14 -
8 Installing the T622/T622G	15 -
8.1 Installing GPS and GSM Antennas	15 -
8.2 Installing an I/O Cable	15 -
8.2.1 Power Cable/Ground Wire (Pin 1/2)	17 -
8.2.2 ACC and Door Detection (Pin 5/7)	17 -
8.2.3 Output Control (Pin 10/11)	18 -
8.2.4 Sensor Input	18 -
8.3 Installing the Camera (RS232 EXT Port)	18 -
8.4 Installing the Garmin Navigator (RS232/485 Port)	19 -
8.5 Mounting the T622/T622G	20 -



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2 Product Overview

The T622/T622G is a brand new high-end vehicle GPS tracker with market-proven quality and precise positioning. In addition to real-time tracking, it supports various peripherals and can be installed into taxies, freight cars, and buses.

2.1 Product Features

2.1.1 Garmin Navigator

After the device is connected to a Garmin navigator, the GPS navigation, information dispatching, and location query functions become available. The device can connect to the Garmin navigator which supports FMI protocol V2.5 or later, and you must purchase the Garmin data cable.

For details about the Garmin navigator, please visit the website:

http://www8.garmin.com/solutions/mobile-resource-management/supported-devices/.

For details about how to install and use the Garmin navigator, see the Garmin Navigator User Guide.

2.1.2 Harsh Acceleration/Braking Alarm

You can detect the harsh acceleration/braking alarm by setting the limit value.

Cautions on device installation:

- 1. The device should be installed into the vehicle according to the following direction.
- 2. The device installation angle cannot exceed 15 degrees.



The default harsh acceleration and braking alarm values are 200 mG and -250 mG respectively.

Accelerate and decelerate alarm			
Accelerate alarm value	200	\$	mG
Decelerate alarm value	-250	\$	mG

Note: The alarm results vary according to the device installation, vehicle model, vehicle weight, and driving behaviors. After the device has been installed properly, you can use the Meitrack Manager software to adjust the harsh acceleration and braking alarm values by every 10 mG. You can also use the D78 command to set the values.

2.1.3 Roaming Mode

On the Meitrack Manager page, device parameters in roaming mode differ from that in non-roaming mode. When the device detects that it is in roaming mode, it will be operated according to roaming parameters. This helps to save network traffic and learn about device working status.

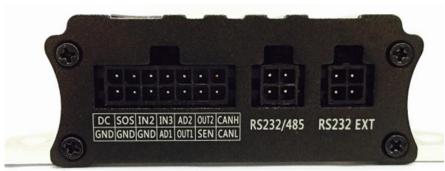
2.1.4 CAN Bus Interface

The device can read CAN bus data of a vehicle that supports the FMS protocol.

The following data can be read: vehicle speed, vehicle control status, accelerator pedal position (%), total fuel consumption, engine rotational speed, total engine run time, total mileage, engine coolant temperature, fuel level, engine torque, ambient temperature, torque at current speed, fuel consumption rate, axle weight, service distance, and instantaneous fuel consumption.

Caution:

- 1. To obtain the preceding data, the vehicle must support the FMS protocol.
- 2. Install the device based on vehicle types. Connect vehicle's CANH and CANL wires to tracker's CANH and CANL connectors respectively.



2.1.5 GPS Data Filtering

The GPS data filtering function can ensure GPS data accuracy and eliminate static drift.

You can set the following parameters by Meitrack Manager: **GPS speed range**, **GPS positioning accuracy**, and **Number of GPS satellites**. When the GPS data filtering function is enabled, if all conditions are met, GPS data will be updated. Otherwise, GPS data will be invalid.

all conditions	below are met, GPS data will be updated.)
10	➡ To 200 ♣ km/h
1.0	\$ *10
5	\$
	10

Note: This function can be enabled by Meitrack Manager.



2.1.6 Activating Output by Event

You can activate output by event.

For example:

- 1. When speeding is detected, the device can control buzzer sounds.
- 2. When unauthorized ignition or GPS antenna cut-off is detected, the engine will not be able to start.
- 3. When RFID triggering is detected, the device can control the vehicle door.
- 4. When input or output status is detected, the output will be active or inactive.

Event	SMS Header	V	alue	1343104	2850				GPR	S Photo	Ou	tput
				SMS	Call	SM	IS Call	SMS D	Call		1	2
SOS Pressed	SOS				✓					~	v	v
Input 2 Active	Door Open				>							
Input 3 Active	Ignition On				Y							
Input 1 Inactive	In1 Inactive								v			
Input 2 Inactive	Door Close								~			
Input 3 Inactive	Ignition Off								v			
Output port												
Trigger time	100 🗘 *10ms	Duty cycle	50 \$	%	-Output 2		200	\$ *10ms	Duty cycle	80	\$ %	
	Low level	PWM period	5000 \$	us	Trigger mo	. [Low level		PWM period	6000	tus	

3 Product Functions and Specifications

3.1 Product Functions

3.1.1 Position Tracking

- GPS + GSM positioning
- Real-time location query
- Track by time interval
- Track by distance
- Cornering report
- Speeding alarm
- Track by mobile phone
- Harsh acceleration/braking alarm
- GPS data filtering

3.1.2 Anti-Theft

- SOS alarm
- GPS antenna cut-off alarm
- External power supply cut-off alarm
- GPS blind spot alarm
- Remote vehicle fuel/power cut-off
- Engine or vehicle door status alarm



- Towing alarm
- Polygonal geo-fence alarm
- Fuel monitoring

3.1.3 Other Functions

- SMS/GPRS (TCP/UDP) communication (Meitrack protocol)
- Built-in 8 MB buffer for recording driving routes (storing 256 SMS cache records. The quantity of GPRS cache and GPS logs can be set and their sum is a fix value.)
- Mileage report
- Low power alarm for internal battery
- 3-axis accelerometer
- Over-the-Air (OTA) update
- Activate output by event
- Stop Moving and Start Moving alarms
- Online Parameter Editor
- Support a CAN bus interface.
- Set device parameters in roaming mode. (Switch to roaming parameters when the device is in roaming mode.)

3.1.4 Functions of Optional Accessories

Optional Access	ories	Function
A53 resistive fue	l level sensor	Check the fuel level.
A52 digital temp	erature sensor + A61 sensor box	Check temperature.
iButton		Identify the driver ID and grant permission to start the vehicle.
		Monitor driver attendance by RFID report.
Super magnet		Fix the device in place.
2 RS232 ports	Garmin navigator	Used for vehicle navigation and tracking
	Camera (Used with a Micro SD card)	Take photos.
LED display		Display advertisements and announcements.
Liquid level sensor (LLS) sensor		Check the fuel level and detect a fuel theft alarm.
A76 ultrasonic fuel level sensor		Check the fuel level and detect a fuel theft alarm.

3.2 Specifications

Item	Specifications
Dimension	105 mm x 65 mm x 26 mm
Weight	190g
Power supply	DC 11–36 V/1.5 A
Backup battery	400 mAh/3.7 V
Power consumption	Current in standby mode: 65mA
Operating temperature	-20°C to 55°C
Operating humidity	5% to 95%
Working hour	53 hours in power-saving mode
	5.5 hours in normal mode



LED indicator	Green indicator showing the GSM signal		
	Blue indicator showing the GPS signal		
Button/Switch	1 power button		
Memory	8 MB buffer		
Sensor	3-axis accelerometer (used to wake the device up by vibration and detect towing		
	alarms)		
Frequency band	Т622		
	GSM/GPRS: 850/900/1800/1900 MHz		
	T622G		
	UMTS/HSDPA: 800/850/900/1900/2100 MHz		
	GSM/GPRS: 850/900/1800/1900 MHz		
GPS sensitivity	-161 dB		
Positioning accuracy	10m		
I/O port	3 digital inputs (1 negative trigger, 1 positive trigger, and 1 positive/negative		
	selectable trigger)		
	2 analog detection inputs		
	2 outputs		
	1 RS232 EXT port		
	1 RS232/485 port		
	1 USB port		
	1 digital sensor port		
	1 CAN bus interface		

4 T622/T622G and Accessories

T622/T622G and standard accessories:



Camera

Garmin navigator

iButton

LLS sensor

A53 fuel level sensor









A52 digital temperature sensor + A61 sensor box

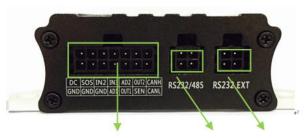
LED display

A76 ultrasonic fuel level sensor

5 Appearance







Power/Input/Output.port+ RS232/485.port+ RS232.EXT.port+

6 First Use

6.1 Installing the SIM Card

- 1. Loosen the screws, and remove the front cover of the T622/T622G.
- 2. Insert the SIM card into the card slot with its gold-plated contacts facing towards the Printed Circuit Board (PCB).
- 3. Close the cover, and tighten the screws.

Note:

- Power off the device before installing the SIM card.
- Ensure that the SIM card has sufficient balance.
- Ensure that the phone card PIN lock has been closed properly.
- Ensure that the SIM card in the device has subscribed the caller ID service if you want to use your authorized phone number to call the device.





6.2 Charging the Device

When you use the device for the first time, connect the device GND (-Black) and Power (+Red) wires to 12 V or 24 V external power supply for charging. Ensure that the device is charged at least two hours. Eight hours are recommended. The device can be installed on a vehicle only after it is configured and tested.

6.3 LED Indicator

Press and hold down the power button for 3–5 seconds to start the device.

GPS Indicator (Blue)				
Steady on	A button or an input is triggered.			
Blink (every 0.1 seconds)	The device is being initialized or the battery power is low.			
Blink (0.1 seconds on and 2.9 seconds off)	A GPS signal is received.			
Blink (1 second on and 2 seconds off)	No GPS signal is received.			
GSM Indicator (Green)				
Steady on	A call is coming in or a call is being made.			
Blink (every 0.1 seconds)	The device is being initialized.			
Blink (0.1 seconds on and 2.9 seconds off)	A base station signal is received.			
Blink (1 second on and 2 seconds off)	No base station signal is received.			

6.4 Configuring Device Parameters by Meitrack Manager

This section describes how to use Meitrack Manager to configure the device on a computer. Procedure:



- 1. Install the USB-to-serial cable driver and Meitrack Manager.
- 2. Connect the device to a computer by using the USB-to-serial cable.
- 3. Run Meitrack Manager, then the following dialog box will appear:

5		×
C	Meitrack Manage Waiting for connecting.	er
	Auto Choose	

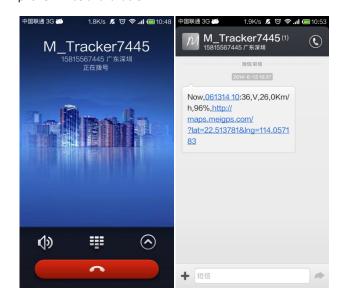
4. Turn on the device, then Meitrack Manager will detect the device model automatically and the parameter page will appear accordingly.

For details about MEITRACK Manager, see the MEITRACK Manager User Guide.

6.5 Tracking by Mobile Phone

Call or send the **0000,A00** command by SMS to the device's SIM card number. The device will reply to an SMS with a map link. Click the SMS link. The device's location will be displayed on Google Maps on your mobile phone.

Note: Ensure that the device's SIM card number has subscribed the caller ID service. Otherwise, the tracking function by mobile phone will be unavailable.



SMS example:

Now,061314 10:36,V,26,0Km/h,96%,http://maps.meigps.com/?lat=22.513781&lng=114.057183

The following table describes the SMS format:

Parameter	Description	Remarks
Now	Indicates the current location.	SMS header: indicates the current location or the alarm type.
061314 10:36	Indicates the date and time in MMDDYY hh:mm format.	None
V	The GPS is invalid.	A = Valid



		V = Invalid		
26	Indicates the GSM signal strength.	Value: 1–32		
		The larger the value is, the stronger the		
		signal is. If the value is greater than 12,		
		GPRS reaches the normal level.		
0Km/h	Indicates the speed.	Unit: km/h		
96%	Indicates the remaining battery power.	None		
http://maps.meigps.co	Indicates the map link.	None		
m/?lat=22.513781&lng	Latitude: 22.513781			
=114.057183	Longitude: 114.057183			



6.6 Common SMS Commands

6.6.1 Setting Authorized Phone Numbers – A71

SMS sending: 0000,A71,Phone number 1,Phone number 2,Phone number 3 SMS reply: IMEI,A71,OK Description: Phone number: A phone number has a maximum of 16 bytes. If no phone numbers are set, leave them blank. Phone numbers are empty by default. Phone number 1/2/3: SOS phone numbers. When you call the tracker by using these phone numbers, you will receive SMS notification about the location, geo-fence alarm and low power alarm. If you need to delete all authorized phone numbers, send **0000,A71**. When the SOS button is pressed, the tracker will dial phone numbers 1, 2, and 3 in sequence. The tracker will stop dialing when a phone number responds. Example: Sending: 0000,A71,13811111111,13822222222,1383333333 Reply: 353358017784062,A71,OK



6.6.2 Setting the Smart Sleep Mode – A73

SMS sending: 0000,A73,Sleep level

SMS reply: IMEI,A73,OK

Description:

When the sleep level is **0**, the sleep mode is disabled (default).

When the sleep level is **1**, the tracker enters the normal sleep mode. The GSM module always works, and the GPS module occasionally enters the sleep mode. The tracker works 25% longer in the normal sleep mode than that in the normal working mode. This mode is not recommended for short interval tracking; this will affect the route precision.

When the sleep level is **2**, the tracker enters the deep sleep mode. If no event (SOS, button changes, incoming calls, SMSs, or vibration) is triggered after five minutes, the GPS module will stop working, and the GSM module will enter sleep mode. Once an event is triggered, the GPS and GSM modules will be woken up.

Note: In any condition, you can use an SMS command to disable the sleep mode, and then the tracker exits the sleep mode and returns back to the normal working mode.

Example:

Sending: 0000,A73,2 Reply: 353358017784062,A73,OK

6.6.3 Setting GPS Data Filtering – D71

SMS sending: 0000,D71,X,Y1,Y2,Y3,Y4

SMS reply: IMEI,D71,OK

Description:

X: Whether to enable the GPS data filtering function. 1: Enable the function. 0: Disable the function (default).

Y1: indicates the minimum value of the driving speed. Value range: 0–999 km/h. When the driving speed is greater than Y1, GPS data will be updated.

Y2: indicates the maximum value of the driving speed. Value range: 0–999 km/h. When the driving speed is less than Y2, GPS data will be updated.

Y3: indicates the number of satellites. Value range: 0–99. When the number of satellites is greater than **Y3**, GPS data will be updated.

Y4: indicates the positioning accuracy. Unit: x10. Value range: 0–999. When the positioning accuracy value is less than Y4, GPS data will be updated.

When the GPS data filtering function is enabled, if all conditions of Y1, Y2, Y3 and Y4 are met, GPS data will be updated.

The GPS data filtering function can eliminate static drift, but it will affect the route precision.

Example:

Sending: 0000,D71,1,5,225,8,9

Reply: 353358017784062,D71,OK

6.6.4 Setting Output Triggering – D72

SMS sending: 0000,D72,X,Y1,Y2,Y3,Y4

SMS reply: IMEI,D72,OK

Description:

X: Select an output port. 1: OUT1. 2: OUT2.

Y1: indicates the output time when an event is triggered. Unit: 10 ms. Value range: 0–4294967295.

Y2: Value: 0, 1, and 2.



- 0: Output high level.
- 1: Output low level (default).
- **2**: Output PWM wave.
- **Y3**: indicates the PWM duty cycle. Value range: 0–100.

Y4: indicates the PWM period. Unit: μ s. Value range: 2000–50000000.

Configure output triggering according to your requirements. The low level is output by default. The PWM duty cycle and period are available for PWM wave output only.

Example:

Sending: 0000,D72,1,0,0

Reply: 353358017784062,D72,OK

6.6.5 Allocating GPRS Cache and GPS Log Storage Space – D73

SMS sending: 0000,D73,X,Y

SMS reply: IMEI,D73,OK

Description:

X: Set the storage percentage of GPRS cache. Decimal in percentage.

Y: Set the storage percentage of GPS logs. Decimal in percentage.

The sum of X and Y must be 100.

If data is stored in internal memory which has 8 MB capacity, GPRS cache and GPS logs occupy 50% of the total capacity respectively by default (that is, 8,190 GPRS cache records and 65,536 GPS logs).

At most 16,384 GPRS cache records and 131,072 GPS logs are allowed.

Example:

Sending: 0000,D73,70,30

Reply: 353358017784062,D73,OK

For details about SMS commands, see the *MEITRACK SMS Protocol*.

Note:

- 1. The default SMS command password is **0000**. You can change the password by using Meitrack Manager and SMS command.
- 2. The device can be configured by SMS commands with a correct password. After an authorized phone number is set, only the authorized phone number can receive the preset SMS event report.

7 Logging In to MS03 Tracking System

Visit http://ms03.trackingmate.com, enter the user name and password, and log in to the MS03. (Purchase the login account from your provider.)

For more information about how to add a tracker, see the *MEITRACK GPS Tracking System MS03 User Guide* (chapter 4 "Getting Started").

The MS03 supports the following functions:

- Track by time interval or distance.
- Query historical trips.
- Set polygonal geo-fences.
- Bind driver and vehicle information.
- View various reports.
- Send commands in batches.



• Support OTA updates.

For details, see the MEITRACK GPS Tracking System MS03 User Guide.

8 Installing the T622/T622G

8.1 Installing GPS and GSM Antennas



Connect the GSM antenna to the connector which is labeled "GSM". The GSM antenna is non-directional, so you can hide it in any place of a vehicle.

Connect the GPS antenna to the connector which is labeled "GPS". It is recommended that the antenna is facing up to the sky and the antenna side with words is downwards. Secure the antenna by using double sided tapes.

Note: Do not install the GPS antenna at a metal covered place.

8.2 Installing an I/O Cable

The I/O cable is a 14-pin cable, including the power, analog input, digital temperature sensor input, negative/positive input and output, and CAN bus interfaces.



1	3	5	7	9	11	13
Power (+)	Input 1	Input 2	Input 3	Fuel level sensor	Output 2	CANH
2	4	6	8	10	12	14
GND (-)	GND (-)	GND (-)	AD input 1	Output 1	Digital sensor/iButton	CANL

Pin Number	Color	Description
1 (Power +)	Red	Positive charge of the power input, connected to the positive
		charge of the vehicle battery. Input voltage: 11–36 V. 12 V is
		recommended.
2 (GND)	Black	Ground wire, connected to the negative charge of the vehicle
		battery or to the negative terminal.

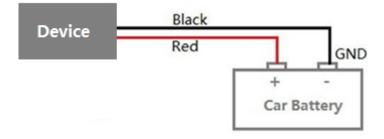
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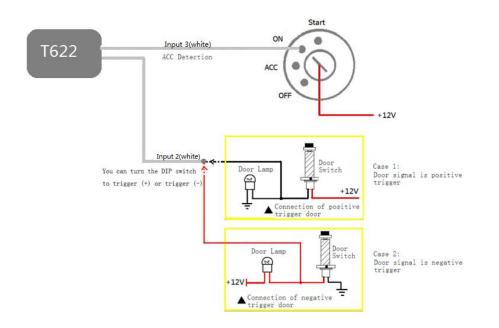
3 (Input 1)	White	Digital input 1, negative trigger (SOS button by default)			
4 (GND)	Black	Ground wire, connected to input 1 (SOS button)			
5 (Input 2)	White	Digital input 2. Positive trigger by default. You can switch to			
		negative trigger.			
		Connect to a door trigger signal cable to detect vehicle door			
		status.			
6 (GND)	Black	Ground wire			
		It can be used as a ground wire connected to an analog sensor.			
7 (Input 3)	White	Digital input 3 (positive trigger)			
		Connect to the vehicle ACC cable by default to detect the vehicle			
		ACC status.			
8 (AD Input 1)	Blue	Analog input 1 with 12-bit resolution and valid voltage 0–6.6 V			
		Connect to an external sensor, such as the fuel level sensor.			
9 (Fuel level sensor	Blue	Analog input 2 with 12-bit resolution and valid voltage 0–6.6 V			
input)		The AD cable is equipped with a white plug. It is connected to the			
		A53 fuel level sensor by default.			
10 (Output 1)	Yellow	Output 1			
		Default: low level (0 V)			
		Invalid: open collector			
		Maximum voltage for output open collector (invalid): 40 V			
		Maximum current: 400 mA			
		High level triggering mode and PWM triggering mode are allowed			
		to set.			
		Connect to an external relay to remotely cut off the vehicle fue			
		cable or engine power supply.			
11 (Output 2)	Yellow	Output 2			
		Valid: low level (0 V)			
		Invalid: open collector			
		Maximum voltage for output open collector (invalid): 40 V			
		Maximum current: 400 mA			
		High level triggering mode and PWM triggering mode are allowed			
		to set.			
		Connect to an external relay to remotely cut off the vehicle fue			
		cable or engine power supply.			
12 (Digital sensor input	Green	TTL3.3V level			
port/iButton)		Connect to the A52 digital temperature sensor by default by using			
		the A61 sensor box. It also can be connected to iButton.			
		Note: The DC or AC voltage that is greater than 3.3 V is not			
		allowed. Otherwise, the device may be damaged.			
13 (CANH)	Orange and white	Used to connect a CAN bus peripheral.			
14 (CANL)	Orange	Used to connect a CAN bus peripheral.			

8.2.1 Power Cable/Ground Wire (Pin 1/2)

Connect the power cable (red) and ground wire (black) to the positive and negative charges of the vehicle battery respectively.



8.2.2 ACC and Door Detection (Pin 5/7)

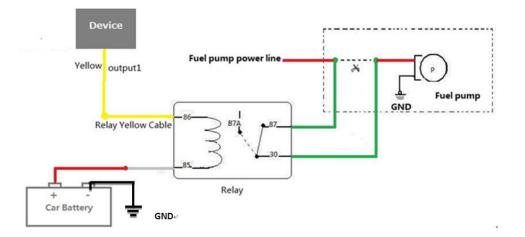


Note:

- 1. If input 3 is connected to the "ACC" position, after the engine is started, the platform will read it as ON-OFF-ON. If input 3 is connected to the "Start" position, after the engine is started, the platform will read it as OFF-ON-OFF. If installed correctly, after the engine is started, the platform will read it as OFF-ON.
- 2. Input 2 is the positive or negative selectable start cable. By default it is positive. Install and configure the cable according to your requirements.



8.2.3 Output Control (Pin 10/11)



Note: To implement remote fuel/power cut-off, connect the relay to the fuel pump power cable or to the engine power cable in series.

8.2.4 Sensor Input

For pin 8 analog input 1, a sensor whose output voltage ranges from 0 V to 6.6 V can be installed. The analog voltage calculation formula is as follows:

Voltage = AD/100

Pin 10 is connected to the A53 fuel level sensor by default. You can install the sensor without calculation formula added on the platform. For details, see the *MEITRACK Fuel Level Sensor User Guide*.

Pin 12 is connected to A61+A52 temperature sensor by default. You can install the sensor without calculation formula added on the platform. For details, see the *MEITRACK Temperature Sensor User Guide*.

Note:

- The white plug on the T622/T622G harness consists of the power cable (red), ground wire (black), AD2 cable (blue), and SEN cable (blue).
- The T622/T622G can connect to a maximum of two A61 sensor boxes. You can install a maximum of eight A52 temperature sensor ports. For details, see the *MEITRACK Temperature Sensor User Guide*.

8.3 Installing the Camera (RS232 EXT Port)





Pin Number	Color	Description
1	Red	Power output
		Output voltage: 5 V
2	Black	Ground wire
3	Green	RX, T622/T622G receives data from the camera.
4	White	TX, T622/T622G sends data to the camera.

After the camera is installed, you must configure related parameters by Meitrack Manager.

-Peripheral-							
RS232/485	Garmin navigation	•	Setting	Baud rate	▼ 9600	-	
RS232 EXT	CAMERA	•	Setting	Baud rate	▼ 115200	-	Write

Note: Besides the camera, the RS232 EXT port can connect to the LED display, Garmin navigator, or LLS sensor.

8.4 Installing the Garmin Navigator (RS232/485 Port)



Pin Number	Color	Description	
1	Red	Power output	
		Output voltage: 5 V	
2	Black	Ground wire	
3	Green	RX, T622/T622G receives data from the Garmin navigator.	
4	White	TX, T622/T622G sends data to the Garmin navigator.	

After the Garmin navigator is installed, you must configure related parameters by Meitrack Manager.

Γ	Peripheral							
	RS232/485	Garmin navigation	-	Setting	Baud rate	▼ 9600	-	
	RS232 EXT	CAMERA	•	Setting	Baud rate	▼ 115200	-	Write

Note:

- 1. The RS232/485 port is RS232 or RS485 port. It is the RS232 port by default. The RS485 port is reserved as an optional port.
- 2. Besides the Garmin navigator, the RS232/485 port can connect to the camera, LLS sensor, or A76 ultrasonic fuel level sensor.



8.5 Mounting the T622/T622G

Tighten the four screws shown in the following figure.



If you have any questions, do not hesitate to email us at info@meitrack.com.